Updating Knowing How

Raul Fervari

Logics, Interaction and Intelligent Systems Group (LIIS),

FAMAF-UNC / CONICET, Argentina

(Joint work with C. Areces, A. Saravia, F. Velázquez-Quesada)

FM&AI Working Group - LMF - France - 2023

- Usually, epistemic logic is about "knowing that" (Hintikka 1962):
 - John knows that it is raining in Paris,
 - $\circ~$ the robot knows that it is standing next to a wall...

- Usually, epistemic logic is about "knowing that" (Hintikka 1962):
 - John knows that it is raining in Paris,
 - the robot knows that it is standing next to a wall...
 - Typically, modal formulas $K_i \varphi$ expressing "agent i knows that φ ".

- Usually, epistemic logic is about "knowing that" (Hintikka 1962):
 - $\circ~$ John knows that it is raining in Paris,
 - the robot knows that it is standing next to a wall...
 - $\circ~$ Typically, modal formulas $K_i \varphi$ expressing "agent i knows that φ ".
- Study other patterns of reasoning:
 - knowing why,
 - knowing whether,
 - knowing who,
 - knowing how.

- Autonomous agent: intelligent entities operating in a given environment (perception, decision making, etc).
- Related to the abilities of the agents to achieve a certain goal.
- Inspired by AI planning.
- Interpreted as: there exists a proper course of action (sequence of actions) that the agent can take to achieve the goal.

- Autonomous agent: intelligent entities operating in a given environment (perception, decision making, etc).
- Related to the abilities of the agents to achieve a certain goal.
- Inspired by AI planning.
- Interpreted as: there exists a proper course of action (sequence of actions) that the agent can take to achieve the goal.
 - $\circ~$ What "proper" means?
 - Different costs?
 - How to update the agents' knowledge (how)?

History of Knowing How Approaches

- Knowing that + Abilities (Lespérance et al. 2000), (Herzig & Troquard 2006), etc.
- A single binary modality for knowing how $Kh(\psi, \varphi)$ and variants: (Wang 2015).
- Knowing how + knowing that (Fervari et al. 2017).
- Semantics based on indistinguishability/uncertainty between plans (Areces et al. 2021).

History of Knowing How Approaches

- Knowing that + Abilities (Lespérance et al. 2000), (Herzig & Troquard 2006), etc.
- A single binary modality for knowing how $Kh(\psi, \varphi)$ and variants: (Wang 2015).
- Knowing how + knowing that (Fervari et al. 2017).
- Semantics based on indistinguishability/uncertainty between plans (Areces et al. 2021).

We argue the latter enables us to develop a full theory of epistemic logic of knowing how.

An LTS is a tuple $S = \langle S, \{R_a\}_{a \in Act}, V \rangle$ where:

• S is a countable set of states • V : $Prop \rightarrow 2^{S}$

• $R_a \subseteq S \times S$, for each $a \in Act$.

An LTS is a tuple $\mathcal{S}=\langle S, \{R_a\}_{a\in Act}, V\rangle$ where:

• S is a countable set of states

• V : Prop
$$\rightarrow 2^{S}$$

• $R_a \subseteq S \times S$, for each $a \in Act$.



An LTS is a tuple $\mathcal{S}=\langle S, \{R_a\}_{a\in Act}, V\rangle$ where:

• S is a countable set of states

• V : Prop
$$\rightarrow 2^{S}$$

• $R_a \subseteq S \times S$, for each $a \in Act$.



A transition *a* from w_1 to w_2 is read as "after executing action *a* at state w_1 , the agent reaches state w_2 ".

An LTS is a tuple $\mathcal{S} = \langle S, \{R_a\}_{a \in Act}, V \rangle$ where:

• S is a countable set of states

• V : Prop
$$\rightarrow 2^{S}$$

• $R_a \subseteq S \times S$, for each $a \in Act$.



A transition *a* from w_1 to w_2 is read as "after executing action *a* at state w_1 , the agent reaches state w_2 ".

For a set of actions Act, a plan σ is an element from Act^{*} (finite sequences of symbols from Act, such as *a*, *ab* and the empty plan ϵ).

A plan must be fail-proof: each partial execution must be completed.



ab is not SE at w1

A plan must be fail-proof: each partial execution must be completed.



ab is not SE at w1

Definition:

A plan σ is strongly executable (SE) at $u \in S$ iff for all partial execution of σ from u, such an execution can be completed.

• The agent is not aware of the existence of certain plans?

- The agent is not aware of the existence of certain plans?
- The agent is not able to distinguish certain plan from another?

- The agent is not aware of the existence of certain plans?
- The agent is not able to distinguish certain plan from another?
- The agent does not care about the difference among certain plans?

- The agent is not aware of the existence of certain plans?
- The agent is not able to distinguish certain plan from another?
- The agent does not care about the difference among certain plans?

We introduced the notion of epistemic indistinguishability at the level of plans, to fix these issues (Areces et al. 2021).

Uncertainty-based LTS (LTS^U)

An LTS^U is a tuple $S = \langle S, \{R_a\}_{a \in Act}, \{\sim_i\}_{i \in Agt}, V \rangle$ where:

- $\langle S, \{R_a\}_{a \in Act}, V \rangle$ is an LTS,
- ∼_i is an equivalence relation over a non-empty set of plans, for each i ∈ Agt (a set of agent symbols).



Uncertainty-based LTS (LTS^U)

An LTS^U is a tuple $S = \langle S, \{R_a\}_{a \in Act}, \{\sim_i\}_{i \in Agt}, V \rangle$ where:

- $\langle S, \{R_a\}_{a \in \mathsf{Act}}, V \rangle$ is an LTS,
- ~_i is an equivalence relation over a non-empty set of plans, for each i ∈ Agt (a set of agent symbols).



We call U_i the set of equivalence classes (over plans) by \sim_i .

Definition (L_{Kh_i} over LTS^U).

Formulas of the language L_{Kh_i} are given by

 $\varphi ::= p \mid \neg \varphi \mid \varphi \lor \varphi \mid \mathsf{Kh}_i(\varphi, \varphi),$

with $p \in Prop$, and $i \in Agt$ and $a \in Act$.

Definition (L_{Kh_i} over LTS^U).

Formulas of the language L_{Kh_i} are given by

 $\varphi ::= p \mid \neg \varphi \mid \varphi \lor \varphi \mid \mathsf{Kh}_i(\varphi, \varphi),$

with $p \in \text{Prop}$, and $i \in \text{Agt}$ and $a \in \text{Act}$. $\text{Kh}_i(\psi, \varphi)$ is read as "agent *i* knows how to achieve φ given ψ ".

Definition (L_{Kh_i} over LTS^U).

Formulas of the language L_{Kh_i} are given by

 $\varphi ::= p \mid \neg \varphi \mid \varphi \lor \varphi \mid \mathsf{Kh}_i(\varphi, \varphi),$

with $p \in \text{Prop}$, and $i \in \text{Agt}$ and $a \in \text{Act. } \text{Kh}_i(\psi, \varphi)$ is read as "agent i knows how to achieve φ given ψ ".

 $\mathcal{S}, w \models \mathsf{Kh}_i(\psi, \varphi)$ iff there exists a set of plans $\pi \in \mathsf{U}_i$ such that:

- 1. each plan in π is SE at every ψ -state; and
- 2. from ψ -states, each plan in π always ends at φ -states.

Definition (L_{Kh_i} over LTS^U).

Formulas of the language L_{Kh_i} are given by

 $\varphi ::= p \mid \neg \varphi \mid \varphi \lor \varphi \mid \mathsf{Kh}_i(\varphi, \varphi),$

with $p \in \text{Prop}$, and $i \in \text{Agt}$ and $a \in \text{Act. } \text{Kh}_i(\psi, \varphi)$ is read as "agent *i* knows how to achieve φ given ψ ".

 $\mathcal{S}, w \models \mathsf{Kh}_i(\psi, \varphi)$ iff there exists a set of plans $\pi \in \mathsf{U}_i$ such that:

- 1. each plan in π is SE at every ψ -state; and
- 2. from ψ -states, each plan in π always ends at φ -states.

Property:

Define
$$A\varphi := \bigvee_{i \in Agt} Kh_i(\neg \varphi, \bot)$$
, we have:

 $\mathcal{S}, w \models A\varphi$ iff for all $v, \mathcal{S}, v \models \varphi$;

i.e., A is the standard universal modality (and its dual: $E\varphi := \neg A \neg \varphi$).



 $S, w_1 \models \neg \mathsf{Kh}_i(p, r)$



 $S, w_1 \models \neg \mathsf{Kh}_i(p, r)$ take $\pi = \{a, ab\}$:



 $S, w_1 \models \neg \mathsf{Kh}_i(p, r)$ take $\pi = \{a, ab\}$: - *a* is SE at w_1 (*p*-state), and takes from *p*-states to *r*-states.



 $S, w_1 \models \neg \mathsf{Kh}_i(p, r)$ take $\pi = \{a, ab\}$: - *a* is SE at w_1 (*p*-state), and takes from *p*-states to *r*-states. - *ab* is not SE at w_1 (*p*-state).



 $S, w_1 \models \neg \mathsf{Kh}_i(p, r)$ take $\pi = \{a, ab\}$: - *a* is SE at w_1 (*p*-state), and takes from *p*-states to *r*-states. - *ab* is not SE at w_1 (*p*-state). - thus, $\pi = \{a, ab\}$ is not SE at w_1 .



 $S, w_1 \models \neg \mathsf{Kh}_i(p, r)$ take $\pi = \{a, ab\}$: - *a* is SE at w_1 (*p*-state), and takes from *p*-states to *r*-states. - *ab* is not SE at w_1 (*p*-state). - thus, $\pi = \{a, ab\}$ is not SE at w_1 .

 $\mathcal{S}, w_1 \models \mathsf{Kh}_i(p, r)$



 $S, w_1 \models \neg \mathsf{Kh}_i(p, r)$ take $\pi = \{a, ab\}$: - *a* is SE at w_1 (*p*-state), and takes from *p*-states to *r*-states. - *ab* is not SE at w_1 (*p*-state). - thus, $\pi = \{a, ab\}$ is not SE at w_1 .

 $\begin{aligned} \mathcal{S}, w_1 &\models \mathsf{Kh}_j(p, r) \\ \text{take } \pi' &= \{a\}: \\ - a \text{ is SE at } w_1 \text{ (}p\text{-state), and} \\ \text{takes from } p\text{-states to } r\text{-states.} \\ - \text{ thus, } \pi' &= \{a\} \text{ works as a witness.} \end{aligned}$

- Updating the LTS = update what an agent can do.
- Updating the relation ~_i (or the set U_i) = epistemic updates (affecting the "knowing how").

- Updating the LTS = update what an agent can do.
- Updating the relation ~_i (or the set U_i) = epistemic updates (affecting the "knowing how").
- **Proposal:** refining the indistinguishability between plans, i.e., making plans distinguishable for the agent.

Definition (L_{Ref} formulas)

$$\varphi ::= p \mid \neg \varphi \mid \varphi \lor \varphi \mid \mathsf{Kh}_i(\varphi, \varphi) \mid \langle \sigma_1 \not\sim \sigma_2 \rangle \varphi$$

Definition (L_{Ref} formulas)

$$\varphi ::= p \mid \neg \varphi \mid \varphi \lor \varphi \mid \mathsf{Kh}_i(\varphi, \varphi) \mid \langle \sigma_1 \not\sim \sigma_2 \rangle \varphi$$

 $\langle \sigma \not\sim \sigma_2 \rangle \varphi$: "After it is stated that plans σ_1 and σ_2 are distinguishable, φ holds."



•
$$S, w \models \mathsf{Kh}_i(p, r) \text{ and } S, w \models \langle a \not\sim b \rangle \mathsf{Kh}_i(p, r).$$



• $S, w \models \mathsf{Kh}_i(p, r) \text{ and } S, w \models \langle a \not\sim b \rangle \mathsf{Kh}_i(p, r).$

preserves knowledge



• $S, w \models \mathsf{Kh}_i(p, r) \text{ and } S, w \models \langle a \not\sim b \rangle \mathsf{Kh}_i(p, r).$

preserves knowledge

• $\mathcal{S}, w \not\models \mathsf{Kh}_j(p, r)$



• $S, w \models \mathsf{Kh}_i(p, r) \text{ and } S, w \models \langle a \not\sim b \rangle \mathsf{Kh}_i(p, r).$

preserves knowledge

• $S, w \not\models \mathsf{Kh}_j(p, r)$ but $S, w \models \langle a \not\sim b \rangle \mathsf{Kh}_j(p, r);$



• $S, w \models \mathsf{Kh}_i(p, r) \text{ and } S, w \models \langle a \not\sim b \rangle \mathsf{Kh}_i(p, r).$

preserves knowledge

- $S, w \not\models \operatorname{Kh}_j(p, r)$ but $S, w \models \langle a \not\sim b \rangle \operatorname{Kh}_j(p, r);$
 - generates new knowledge

Property:

 L_{Ref} is more expressive than L_{Kh_i} .

Property:

 L_{Ref} is more expressive than L_{Kh_i} .

Proof: Let S and S' be the LTSs below, with $U_i := \{\{a\}\}\)$ and $U'_i := \{\{a, b\}\}$:



 $\mathcal{S}, w \models \neg \langle a \not\sim b \rangle \mathsf{Kh}_i(p,q) \text{ while } \mathcal{S}', w \models \langle a \not\sim b \rangle \mathsf{Kh}_i(p,q).$

Uniform substitution is an standard property in axiomatizing the logic. If φ is valid, then $\varphi[p/\psi]$ is also valid.

Uniform substitution

Uniform substitution is an standard property in axiomatizing the logic.

If φ is valid, then $\varphi[p/\psi]$ is also valid.

Property:

Uniform substitution fails in L_{Ref} .

Uniform substitution

Uniform substitution is an standard property in axiomatizing the logic.

If φ is valid, then $\varphi[p/\psi]$ is also valid.

Property:

Uniform substitution fails in L_{Ref}.

Proof:

Take the formula $\varphi = p \rightarrow \langle a \not\sim b \rangle p$, and the LTS^U S below, with $U_i = \{\{a, b\}\}$:



Uniform substitution

Uniform substitution is an standard property in axiomatizing the logic.

If φ is valid, then $\varphi[p/\psi]$ is also valid.

Property:

Uniform substitution fails in L_{Ref}.

Proof:

Take the formula $\varphi = p \rightarrow \langle a \not\sim b \rangle p$, and the LTS^U S below, with $U_i = \{\{a, b\}\}$:

$$S \qquad w \not p \qquad b \qquad b \qquad b$$

Replace p by $\neg \mathsf{Kh}_i(p,q)$: $\neg \mathsf{Kh}_i(p,q) \rightarrow \langle a \not\sim b \rangle \neg \mathsf{Kh}_i(p,q)$ is not valid.

- This kind of updates increase the expressive power:
 - $\circ~$ Failure of uniform substitution.
 - $\circ~$ No reduction axioms.
- Quite challenging to obtain axiomatizations.

- This kind of updates increase the expressive power:
 - $\circ~$ Failure of uniform substitution.
 - $\circ~$ No reduction axioms.
- Quite challenging to obtain axiomatizations.
- (A) solution: extend the expressivity of the underlying static language.

Definition ($L_{Kh_i,\Box}$)

Formulas of the language $L_{Kh_i,\Box}$ are given by

 $\varphi ::= p \mid \neg \varphi \mid \varphi \lor \varphi \mid \mathsf{Kh}_i(\varphi, \varphi) \mid [a]\varphi,$

with $p \in \text{Prop}$, $i \in \text{Agt}$ and $a \in \text{Act}$. Define: $\langle a \rangle \varphi := \neg[a] \neg \varphi$.

Definition

 $\mathcal{S}, w \models [a] \varphi$ iff for all v s.t. $(w, v) \in \mathsf{R}_a$, $\mathcal{S}, v \models \varphi$.

Action Refinement

Definition $(L_{Kh_i,\Box,[!_-]})$

 $\mathcal{S}, w \models [!a]\varphi \text{ iff } \mathcal{S}^a, w \models \varphi,$

where $a \in Act$ and S^a is as S, except that for all $i \in Agt$ we have:

- $U_i^a = (U_i \setminus \pi) \cup \{\{a\}\}, \text{ if } a \in \pi;$
- $U_i^a = U_i \cup \{\{a\}\}$, otherwise.

Action Refinement

Definition $(L_{Kh_i,\Box,[!_]})$

 $\mathcal{S}, w \models [!a]\varphi \text{ iff } \mathcal{S}^a, w \models \varphi,$

where $a \in Act$ and S^a is as S, except that for all $i \in Agt$ we have:

- $U_i^a = (U_i \setminus \pi) \cup \{\{a\}\}, \text{ if } a \in \pi;$
- $U_i^a = U_i \cup \{\{a\}\}$, otherwise.

Let S be such that $U_i := \{\{a, b\}\}.$



 $\mathcal{S}, w \not\models \mathsf{Kh}_i(p,q) \text{ and } \mathcal{S}, w \models [!b]\mathsf{Kh}_i(p,q).$

- 1. $[!a]p \leftrightarrow p$
- 2. $[!a] \neg \varphi_1 \leftrightarrow \neg [!a] \varphi_1$
- 3. $[!a](\varphi_1 \lor \varphi_2) \leftrightarrow ([!a]\varphi_1 \lor [!a]\varphi_2)$
- 4. $[!a][a]\varphi_1 \leftrightarrow [a][!a]\varphi_1$

- 1. $[!a]p \leftrightarrow p$
- 2. $[!a] \neg \varphi_1 \leftrightarrow \neg [!a] \varphi_1$
- 3. $[!a](\varphi_1 \lor \varphi_2) \leftrightarrow ([!a]\varphi_1 \lor [!a]\varphi_2)$
- 4. $[!a][a]\varphi_1 \leftrightarrow [a][!a]\varphi_1$
- 5. [!a]Kh_i(φ_1, φ_2) \leftrightarrow (Kh_i($[!a]\varphi_1, [!a]\varphi_2$) \vee A($[!a]\varphi_1 \rightarrow (\langle a \rangle \top \land [a][!a]\varphi_2)))$

- 1. $[!a]p \leftrightarrow p$
- 2. $[!a] \neg \varphi_1 \leftrightarrow \neg [!a] \varphi_1$
- 3. $[!a](\varphi_1 \lor \varphi_2) \leftrightarrow ([!a]\varphi_1 \lor [!a]\varphi_2)$
- 4. $[!a][a]\varphi_1 \leftrightarrow [a][!a]\varphi_1$
- 5. [!a]Kh_i(φ_1, φ_2) \leftrightarrow (Kh_i($[!a]\varphi_1, [!a]\varphi_2$) \vee A($[!a]\varphi_1 \rightarrow (\langle a \rangle \top \land [a][!a]\varphi_2)))$

Via reduction axioms, we can eliminate all the occurrences of a [!a] modality (i.e., embed $L_{Kh_i,\Box,[!.]}$ into $L_{Kh_i,\Box}$).

Let S be s.t. $U_i := \{\{a, b\}\}, S, w \not\models \mathsf{Kh}_i(p, q) \text{ and } S, w \models [!b]\mathsf{Kh}_i(p, q).$



 $\mathcal{S}, w \models [!b] \mathsf{Kh}_i(p,q)$



Let S be s.t. $U_i := \{\{a, b\}\}, S, w \not\models \mathsf{Kh}_i(p, q) \text{ and } S, w \models [!b]\mathsf{Kh}_i(p, q).$



 $S, w \models [!b] \mathsf{Kh}_i(p,q)$ iff $S, w \models \mathsf{Kh}_i([!b]p, [!b]q) \lor \mathsf{A}([!b]p \to (\langle b \rangle \top \land [b][!b]q))$ (1)

Let S be s.t. $U_i := \{\{a, b\}\}, S, w \not\models \mathsf{Kh}_i(p, q) \text{ and } S, w \models [!b]\mathsf{Kh}_i(p, q).$



 $S, w \models [!b] Kh_i(p,q)$ (5) iff $S, w \models Kh_i([!b]p, [!b]q) \lor A([!b]p \to (\langle b \rangle \top \land [b][!b]q))$ (1) iff $S, w \models Kh_i(p,q) \lor A(p \to (\langle b \rangle \top \land [b]q))$

Axioms	Taut	$\vdash \varphi$ for φ a propositional tautology
	DistA	$dash A(arphi o \psi) o (Aarphi o A\psi)$
	TA	$\vdash A arphi o arphi$
	Dist□	$\vdash [a](arphi ightarrow \psi) ightarrow ([a] arphi ightarrow [a] \psi)$
	A	dash Aarphi o [a]arphi
	4KhA	$\vdash Kh_i(\psi, arphi) o AKh_i(\psi, arphi)$
	5KhA	$dash \neg Kh_i(\psi, arphi) ightarrow A \neg Kh_i(\psi, arphi)$
	KhE	$\vdash (E\psi \wedge Kh_i(\psi, arphi)) ightarrow Earphi$
	KhA	$\vdash (A(\chi \to \psi) \land Kh_i(\psi, \varphi) \land A(\varphi \to \theta)) \to Kh_i(\chi, \theta)$
Rules	MP	$From \vdash \varphi and \vdash \varphi \rightarrow \psi infer \vdash \psi$
	NecA	$From\vdash\varphiinfer\vdashA\varphi$

Theorem

1. The axiom system above is sound and complete for $L_{Kh_i,\Box}$.

Axioms	Taut	$\vdash \varphi$ for φ a propositional tautology
	DistA	$dash A(arphi o \psi) o (Aarphi o A\psi)$
	TA	$\vdash A \varphi o \varphi$
	Dist□	\vdash [a]($\varphi \rightarrow \psi$) \rightarrow ([a] $\varphi \rightarrow$ [a] ψ)
	A	dash Aarphi o [a]arphi
	4KhA	$\vdash Kh_i(\psi, arphi) ightarrow AKh_i(\psi, arphi)$
	5KhA	$dash \neg Kh_i(\psi, arphi) ightarrow A \neg Kh_i(\psi, arphi)$
	KhE	$\vdash (E\psi \wedge Kh_i(\psi, arphi)) ightarrow Earphi$
	KhA	$\vdash (A(\chi \to \psi) \land Kh_i(\psi, \varphi) \land A(\varphi \to \theta)) \to Kh_i(\chi, \theta)$
Rules	MP	$From \vdash \varphi and \vdash \varphi \rightarrow \psi infer \vdash \psi$
	NecA	$From\vdash\varphiinfer\vdashA\varphi$

Theorem

- 1. The axiom system above is sound and complete for $L_{Kh_i,\Box}$.
- 2. The axiom system above + the reduction axioms is sound and complete for $L_{Kh_{i},\square,[1.]}.$

- Preliminary results have been included in (Areces et al.; DALI 2022).
- We extended the expressive power of uncertainty-based knowing how.
- We defined a dynamic modality to update the knowledge, and obtained reduction axioms.
- This idea can be adapted to arbitrary plans, not only actions (i.e., $[!\sigma]\varphi$, with $\sigma \in Act^*$).
- Reduction axioms for the general case.
- Future work: complexity of the logic, other updates.